Real-Time Shadows

“Now this is... this is... well, I guess it’s another snake.”
Why are Shadows Important?

- Depth cue
- Scene Lighting
- Realism
- Contact points
Shadows as a Depth Cue
Shadows as the Origin of Painting

MIT EECS 6.837, Durand
Shadows and Art

• Only in Western pictures (here Caravaggio)
Today

• Shadow Maps
  – Shadow/View Duality
  – Texture Mapping

• Shadow Volumes
Shadow Maps Are Important

• Both in high-end production software...
  – Pixar’s RenderMan
• ... and in real-time rendering (e.g. games)
Shadow/View Duality

- A point is lit if it is visible from the light source

- Shadow computation similar to view computation
Shadow Mapping

- Texture mapping with depth information
- 2 passes
  - Compute shadow map == depth from light source
    - You can think of it as a z-buffer as seen from the light
  - Render final image, check shadow map to see if points are in shadow


MIT EECS 6.837 – Durand
Shadow Map Look Up

- We have a 3D point \((x,y,z)_WS\)
- How do we look up the depth from the shadow map?
- Use the 4x4 perspective projection matrix from the light source to get \((x',y',z')_LS\)
- ShadowMap\((x',y') < z'\)

MIT EECS 6.837 – Durand
Questions?

Plate 52 Grandville, *The Shadows (The French Cabinet)* from *La Caricature*, 1830.
Limitations of Shadow Maps

1. Field of View
2. Bias (Epsilon)
3. Aliasing
1. Field of View Problem

- What if point to shadow is outside field of view of shadow map?
  - Use 6 shadow maps on the faces of a cube
  - ... or use only spot lights O:-)
2. The Bias (Epsilon) Nightmare

- For a point visible from the light source
  \[ \text{ShadowMap}(x', y') \approx z' \]
  - But due to rounding errors the depths never agree exactly

- How can we avoid erroneous self-shadowing?
  - Add bias (epsilon)
2. Bias (Epsilon) for Shadow Maps

ShadowMap(x’,y’) + bias < z’
Choosing a good bias value can be very tricky

Correct image

Not enough bias (“surface acne”)

Way too much bias

MIT EECS 6.837 – Durand
3. Shadow Map Aliasing

- Under-sampling of the shadow map
  - Jagged shadow edges
3. Shadow Map Filtering

- Should we filter the depth?
  (weighted average of neighboring depth values)
- No... filtering depth is not meaningful

(a) Ordinary texture map filtering. Does not work for depth maps.
3. Percentage Closer Filtering

- Instead we need to filter the *result* of the shadow test (weighted average of comparison results)
3. Percentage Closer Filtering

- 5x5 samples
- Nice anti-aliased shadow
- Using a bigger filter produces fake soft shadows
- Setting bias is tricky
Plate 50 Samuel van Hoogstraten, Shadow Theatre. From Inleyding tot de hooghe schoole der schilderkonst 1678.
Shadows in Production

• Often use shadow maps
• Ray casting as fallback in case of robustness issues
Hardware Shadow Maps

- Can be done with hardware texture mapping
  - Texture coordinates u,v,w generated using 4x4 matrix
  - Modern hardware permits tests on texture values
Questions?
Today

• Shadow Maps
• Shadow Volumes
  – (The Stencil Buffer)
Shadow Volumes

- Explicitly represent the volume of space in shadow
- For each polygon
  - Pyramid with point light as apex
  - Include polygon to cap
- Shadow test similar to clipping
Shadow Volumes

• If a point is inside a shadow volume cast by a particular light, the point does not receive any illumination from that light.

• Cost of naive implementation: 
  \#polygons * \#lights
Questions?
Better Shadow Volumes

- Shoot a ray from the eye to the visible point
- Increment/decrement a counter each time we intersect a shadow volume polygon
- If the counter ≠ 0, the point is in shadow
Stencil Buffer

- Tag pixels in one rendering pass to control their update in subsequent rendering passes
  - "For all pixels in the frame buffer" → "For all tagged pixels in the frame buffer"
- Can specify different rendering operations for each case:
  - stencil test fails
  - stencil test passes & depth test fails
  - stencil test passes & depth test passes
Stencil Buffer – Real-time Mirror

- Clear frame, depth & stencil buffers
- Draw all non-mirror geometry to frame & depth buffers
- Draw mirror to stencil buffer, where depth buffer passes
- Set depth to infinity, where stencil buffer passes
- Draw reflected geometry to frame & depth buffer, where stencil buffer passes

See NVIDIA's stencil buffer tutorial http://developer.nvidia.com

also discusses blending, multiple mirrors, objects behind mirror, etc…
Shadow Volumes w/ the Stencil Buffer

Initialize stencil buffer to 0
Draw scene with ambient light only
Turn off frame buffer & z-buffer updates
Draw front-facing shadow polygons
  If z-pass → increment counter
Draw back-facing shadow polygons
  If z-pass → decrement counter
Turn on frame buffer updates
Turn on lighting and redraw pixels with counter = 0
Questions?
If the Eye is in Shadow...

... then a counter of 0 does not necessarily mean lit

3 Possible Solutions:

1. Explicitly test eye point with respect to all shadow volumes
2. Clip the shadow volumes to the view frustum
3. "Z-Fail" shadow volumes
1. Test Eye with Respect to Volumes

- Adjust initial counter value

Expensive

MIT EECS 6.837, Durand
2. Clip the Shadow Volumes

- Clip the shadow volumes to the view frustum and include these new polygons
- *Messy CSG*
3. "Z-Fail" Shadow Volumes

Start at infinity

... 

Draw front-facing shadow polygons
   If z-fail, decrement counter

Draw back-facing shadow polygons
   If z-fail, increment counter
3. "Z-Fail" Shadow Volumes

- Introduces problems with far clipping plane
- Solved by clamping the depth during clipping
Questions?
Optimizing Shadow Volumes

- Use silhouette edges only (edge where a back-facing & front-facing polygon meet)
Shadow Volumes Are Sort of Passé

• It is possible to implement shadow volumes rather efficiently using the stencil buffer
  – John Carmack’s Doom 3 engine did this very well
  – Shadow volumes had their 15 minutes of popularity around that time
  – NVIDIA even came up with hardware acceleration ("UltraShadow")

• Further info
  – Wikipedia

Id Software
Friday, December 3, 2010
Shadow Volumes Are Sort of Passé

• But the need to extract silhouette edges and rasterize the resulting shadow polygons is just too much work when scene complexities and image resolutions grow
Shadow Volumes Are Sort of Passé

• But the need to extract silhouette edges and rasterize the resulting shadow polygons is just too much work when scene complexities and image resolutions grow.

• Shadow maps are bad, but they’re the best we’ve got!
Further Reading on Shadows

• Some recent techniques allow filtering the shadow map instead of just the tests (percentage closer)
  – Works pretty well in some situations, although not general
  – Variance Shadow Maps (Donnelly, Lauritzen I3D 2006)
  – Convolution Shadow Maps
    • Annen et al., SIGGRAPH 2008
    • Annen et al., EGSR 2007

• An interesting hybrid between shadow maps and ray tracing
  – Aila and Laine, Alias-Free Shadow Maps, EGSR 2004
Today

- Shadow Maps
- Shadow Volumes
  - (The Stencil Buffer)
- Deep shadow maps
Deep shadow maps

- Lokovic & Veach, Pixar
- Shadows in participating media like smoke, inside hair, etc.
  - They represent not just depth of the first occluding surface, but the attenuation along the light rays
- Note: shadowing only, no scattering
Visibility function along depth

- Fraction of a pixel occluded, as a function of depth
- Due to
  - small occluders, semi-transparent objects, smoke & volumetric effects

**Figure 3**: Visibility functions in flatland. Each diagram shows a beam of light that starts at the shadow camera origin (i.e. the light source) and passes through a single pixel of the deep shadow map, accompanied by that pixel’s visibility function. (a) The beam’s power is reduced as it passes through consecutive semitransparent surfaces. (b) The blockers are opaque, but each covers only part of the pixel’s area; the emphasized segments of the function correspond to visible portions of the blockers. (c) Passage through smoke reduces the beam’s power in a more continuous manner.
Deep shadow maps

• Preprocess:
  Compute dense visibility function for each pixel of shadow map
  – send lots of rays or rasterize at a high resolution
  – Compress visibility function at each pixel
    • to reduce memory cost

• At render time, shadow query
  – Transform visible point into light coordinates
    • just like shadow maps
  – Read visibility value from compressed function
Compression algorithm

- Approximation: Piecewise linear
- Set an error bound
- Decide which vertices to keep
- Greedy from zero do far

Figure 5: Our compression algorithm. (a) A piecewise linear curve and an illustration of its error bound. (b) Each input vertex defines a target window that constrains the slope of the next output segment. (c) The current slope range is intersected with each target window until it would become empty. (d) The output segment is extended to the current z value with a slope equal to the midpoint of the current slope range, and this process is repeated.
Deep shadow map results

Figure 11: A cloud with pipes. Notice the shadows cast from surfaces onto volumetric objects and vice versa. A single deep shadow map contains the shadow information for the cloud as well as the pipes.
Deep shadow map results

Figure 1: Hair rendered with and without self-shadowing.
Deep shadow map results

- Advantage of deep shadow map over higher-resolution normal shadow map:
  Pre-filtering for shadow antialiasing

(a) Ball with 50,000 hairs
(b) 512 × 512 Normal shadow map
(c) 4k × 4k Normal shadow map
(d) 512 × 512 Deep shadow map
Enables motion blur in shadows

Figure 12: Rapidly moving sphere with and without motion blur.
Questions?
Today

• Shadow Maps
• Shadow Volumes
  – (The Stencil Buffer)
• Deep shadow maps
• Alias-free shadow maps
Alias-free shadow maps

- Aila and Laine,
  [http://www.tml.tkk.fi/~timo/](http://www.tml.tkk.fi/~timo/)
- aka Irregular z-buffer by Johnson et al.
- Following slides by Aila and Laine
Aliasing: resolution issues

[Sen et al. 2003]
Traditional shadow maps:
Step 1. From light source:

- Compute a shadow map (z-buffer)
- Dots are sampling points
  - depth known only at these points
Traditional shadow maps:
Step 2. From camera:

- Samples vs. pixels
- Project each visible sample to light source
- Determine shadow term using shadow map
Traditional shadow maps: Shadow map sampling points

Points where the depth is computed/known ≠ Points where the depth is queried
Idea: why not do it right?

1. Project screen-space samples to image plane of light source
2. Rasterize blocker geometry using them as sampling points
   - Depth known at correct positions 😊
     - same result as shadow rays
Rasterization

Q: How to rasterize using irregular sampling points?

blocker
Rasterization + depth test

1. Test if sampling point covered
   ○ we use edge functions [Pineda88]

2. Depth test

Let’s make it practical!
   ○ hierarchical processing of sampling points
   ○ we use axis-aligned 2D BSP
Properties

- Resolution issues disappear
- Bias term independent of scene
- Semi-transparent shadow receivers
  - simply transform multiple samples per pixel
- Semi-transparent shadow casters
  - can modulate the RGB color of shadows
Performance (1/2)

- Scalability: random triangles @ 1024x768:
  - transformation of samples: ~130ms
  - BSP construction: ~400ms
  - rasterization:
    - 1K: 145ms
    - 10K: 381ms
    - 100K: 1568ms
    - 1M: 8102ms
Performance (2/2)

- 2.9M semi-transparent shadow casting tris @ 1536x1088: 12.6s/frame
- Plenty of room for optimizations
The Irregular Z-Buffer
(papers_0548)

scene contains 98,266 triangles and two light sources, shadows rendered with irregular shadow maps
That’s All For Today!